

# NAG Toolbox for MATLAB

## f08kf

### 1 Purpose

f08kf generates one of the real orthogonal matrices  $Q$  or  $P^T$  which were determined by f08ke when reducing a real matrix to bidiagonal form.

### 2 Syntax

```
[a, info] = f08kf(vect, k, a, tau, 'm', m, 'n', n)
```

### 3 Description

f08kf is intended to be used after a call to f08ke, which reduces a real rectangular matrix  $A$  to bidiagonal form  $B$  by an orthogonal transformation:  $A = QBP^T$ . f08ke represents the matrices  $Q$  and  $P^T$  as products of elementary reflectors.

This function may be used to generate  $Q$  or  $P^T$  explicitly as square matrices, or in some cases just the leading columns of  $Q$  or the leading rows of  $P^T$ .

The various possibilities are specified by the parameters **vect**, **m**, **n** and **k**. The appropriate values to cover the most likely cases are as follows (assuming that  $A$  was an  $m$  by  $n$  matrix):

1. To form the full  $m$  by  $m$  matrix  $Q$ :

```
[a, info] = f08kf('Q', n, a, tau);
```

(note that the array **a** must have at least  $m$  columns).

2. If  $m > n$ , to form the  $n$  leading columns of  $Q$ :

```
[a, info] = f08kf('Q', n, a, tau);
```

3. To form the full  $n$  by  $n$  matrix  $P^T$ :

```
[a, info] = f08kf('P', m, a, tau);
```

(note that the array **a** must have at least  $n$  rows).

4. If  $m < n$ , to form the  $m$  leading rows of  $P^T$ :

```
[a, info] = f08kf('P', m, a, tau);
```

### 4 References

Golub G H and Van Loan C F 1996 *Matrix Computations* (3rd Edition) Johns Hopkins University Press, Baltimore

### 5 Parameters

#### 5.1 Compulsory Input Parameters

- 1: **vect** – string

Indicates whether the orthogonal matrix  $Q$  or  $P^T$  is generated.

**vect** = 'Q'

$Q$  is generated.

**vect** = 'P'

$P^T$  is generated.

*Constraint:* **vect** = 'Q' or 'P'.

2: **k – int32 scalar**

If **vect** = 'Q', the number of columns in the original matrix  $A$ .

If **vect** = 'P', the number of rows in the original matrix  $A$ .

*Constraint:*  $k \geq 0$ .

3: **a(lda,\*) – double array**

The first dimension of the array **a** must be at least  $\max(1, \mathbf{m})$

The second dimension of the array must be at least  $\max(1, \mathbf{n})$

Details of the vectors which define the elementary reflectors, as returned by f08ke.

4: **tau(\*) – double array**

**Note:** the dimension of the array **tau** must be at least  $\max(1, \min(\mathbf{m}, \mathbf{k}))$  if **vect** = 'Q' and at least  $\max(1, \min(\mathbf{n}, \mathbf{k}))$  if **vect** = 'P'.

Further details of the elementary reflectors, as returned by f08ke in its parameter **taup** if **vect** = 'Q', or in its parameter **taup** if **vect** = 'P'.

## 5.2 Optional Input Parameters

1: **m – int32 scalar**

*Default:* The first dimension of the array **a**.

$m$ , the number of rows of the orthogonal matrix  $Q$  or  $P^T$  to be returned.

*Constraint:*  $m \geq 0$ .

2: **n – int32 scalar**

*Default:* The second dimension of the array **a**.

$n$ , the number of columns of the orthogonal matrix  $Q$  or  $P^T$  to be returned.

*Constraints:*

$n \geq 0$ ;  
 if **vect** = 'Q' and  $m > k$ ,  $m \geq n \geq k$ ;  
 if **vect** = 'Q' and  $m \leq k$ ,  $m = n$ ;  
 if **vect** = 'P' and  $n > k$ ,  $n \geq m \geq k$ ;  
 if **vect** = 'P' and  $n \leq k$ ,  $n = m$ .

## 5.3 Input Parameters Omitted from the MATLAB Interface

lda, work, lwork

## 5.4 Output Parameters

1: **a(lda,\*) – double array**

The first dimension of the array **a** must be at least  $\max(1, \mathbf{m})$

The second dimension of the array must be at least  $\max(1, \mathbf{n})$

The orthogonal matrix  $Q$  or  $P^T$ , or the leading rows or columns thereof, as specified by **vect**, **m** and **n**.

2: **info** – int32 scalar

**info** = 0 unless the function detects an error (see Section 6).

## 6 Error Indicators and Warnings

Errors or warnings detected by the function:

**info** =  $-i$

If **info** =  $-i$ , parameter  $i$  had an illegal value on entry. The parameters are numbered as follows:

1: **vect**, 2: **m**, 3: **n**, 4: **k**, 5: **a**, 6: **lda**, 7: **tau**, 8: **work**, 9: **lwork**, 10: **info**.

It is possible that **info** refers to a parameter that is omitted from the MATLAB interface. This usually indicates that an error in one of the other input parameters has caused an incorrect value to be inferred.

## 7 Accuracy

The computed matrix  $Q$  differs from an exactly orthogonal matrix by a matrix  $E$  such that

$$\|E\|_2 = O(\epsilon),$$

where  $\epsilon$  is the *machine precision*. A similar statement holds for the computed matrix  $P^T$ .

## 8 Further Comments

The total number of floating-point operations for the cases listed in Section 3 are approximately as follows:

1. To form the whole of  $Q$ :

$$\frac{4}{3}n(3m^2 - 3mn + n^2) \text{ if } m > n,$$

$$\frac{4}{3}m^3 \text{ if } m \leq n;$$

2. To form the  $n$  leading columns of  $Q$  when  $m > n$ :

$$\frac{2}{3}n^2(3m - n);$$

3. To form the whole of  $P^T$ :

$$\frac{4}{3}n^3 \text{ if } m \geq n,$$

$$\frac{4}{3}m(3n^2 - 3mn + m^2) \text{ if } m < n;$$

4. To form the  $m$  leading rows of  $P^T$  when  $m < n$ :

$$\frac{2}{3}m^2(3n - m).$$

The complex analogue of this function is f08kt.

## 9 Example

```
vect = 'P';
k = int32(6);
a = [-0.57, -1.28, -0.39, 0.25;
     -1.93, 1.08, -0.31, -2.14;
```

```
    2.3,    0.24,    0.4,   -0.35;  
    -1.93,   0.64,  -0.66,    0.08;  
    0.15,   0.3,    0.15,  -2.13;  
    -0.02,   1.03,  -1.43,   0.5];  
tau = [1.442198259457561;  
       1.915944323746201;  
       0;  
       0];  
[a, d, e, tauq, taup, info] = f08ke(a);  
[aOut, info] = f08kf(vect, k, a(1:4, :), taup)
```

```
aOut =  
    1.0000         0         0         0  
         0   -0.4422    0.6732    0.5927  
         0   -0.3788   -0.7391    0.5570  
         0    0.8130    0.0218    0.5818  
  
info =  
         0
```